

# Chapter 30

## Sources of the Magnetic Field



# Biot-Savart Law – Introduction



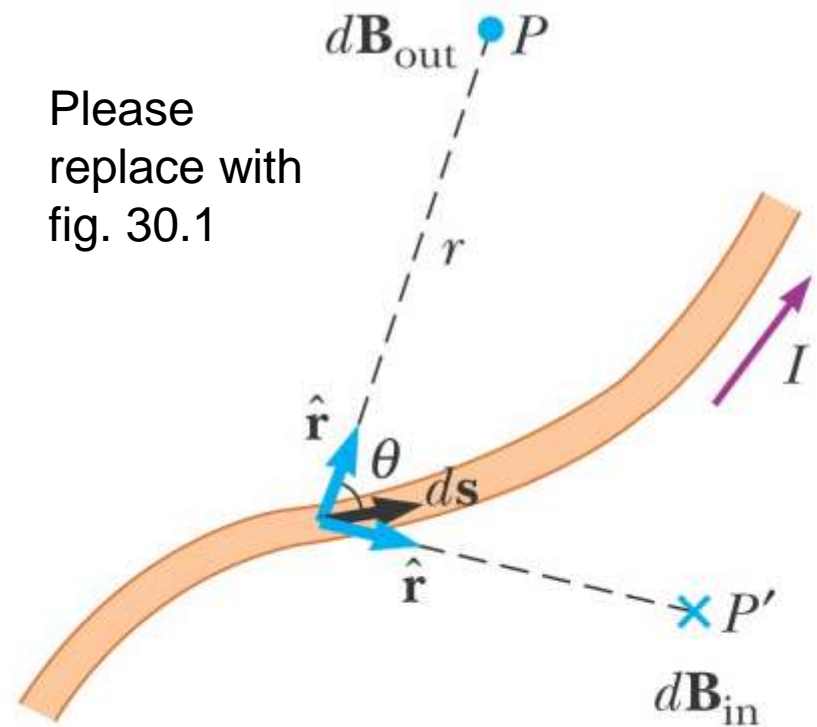
- Biot and Savart conducted experiments on the force exerted by an electric current on a nearby magnet
- They arrived at a mathematical expression that gives the magnetic field at some point in space due to a current



# Biot-Savart Law – Set-Up

- The magnetic field is  $d\vec{B}$  at some point  $P$
- The length element is  $d\vec{s}$
- The wire is carrying a steady current of  $I$

Please  
replace with  
fig. 30.1



# Biot-Savart Law – Observations



- The vector  $d\vec{\mathbf{B}}$  is perpendicular to both  $d\vec{\mathbf{s}}$  and to the unit vector  $\hat{\mathbf{r}}$  directed from  $d\vec{\mathbf{s}}$  toward P
- The magnitude of  $d\vec{\mathbf{B}}$  is inversely proportional to  $r^2$ , where  $r$  is the distance from  $d\vec{\mathbf{s}}$  to P

# Biot-Savart Law – Observations, cont



- The magnitude of  $d\vec{\mathbf{B}}$  is proportional to the current and to the magnitude  $ds$  of the length element  $d\vec{\mathbf{s}}$
- The magnitude of  $d\vec{\mathbf{B}}$  is proportional to  $\sin \theta$ , where  $\theta$  is the angle between the vectors  $d\vec{\mathbf{s}}$  and  $\hat{\mathbf{r}}$



# Biot-Savart Law – Equation

- The observations are summarized in the mathematical equation called the **Biot-Savart law**:

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{I d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

- The magnetic field described by the law is the field *due to* the current-carrying conductor
  - Don't confuse this field with a field *external* to the conductor



# Permeability of Free Space

- The constant  $\mu_0$  is called the **permeability of free space**
- $\mu_0 = 4\pi \times 10^{-7} \text{ T} \cdot \text{m} / \text{A}$



# Total Magnetic Field

- $d\vec{\mathbf{B}}$  is the field created by the current in the length segment  $ds$
- To find the total field, sum up the contributions from all the current elements  $I d\vec{\mathbf{s}}$

$$\vec{\mathbf{B}} = \frac{\mu_o I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

- The integral is over the entire current distribution



# Biot-Savart Law – Final Notes



- The law is also valid for a current consisting of charges flowing through space
- $d\vec{s}$  represents the length of a small segment of space in which the charges flow
  - For example, this could apply to the electron beam in a TV set



# $\vec{B}$ Compared to $\vec{E}$

- Distance
  - The magnitude of the magnetic field varies as the inverse square of the distance from the source
  - The electric field due to a point charge also varies as the inverse square of the distance from the charge

# $\vec{B}$ Compared to $\vec{E}$ , 2



- Direction

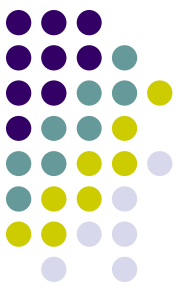
- The electric field created by a point charge is radial in direction
- The magnetic field created by a current element is perpendicular to both the length element  $d\vec{s}$  and the unit vector  $\hat{r}$



# $\vec{B}$ Compared to $\vec{E}$ , 3

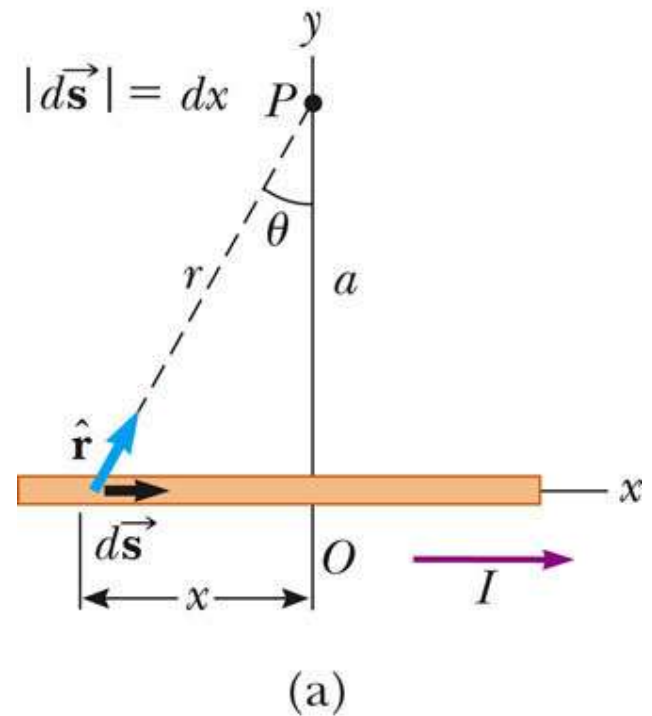
- Source
  - An electric field is established by an isolated electric charge
  - The current element that produces a magnetic field must be part of an extended current distribution
    - Therefore you must integrate over the entire current distribution

# $\vec{B}$ for a Long, Straight Conductor

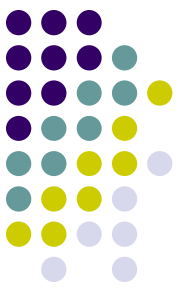


- The thin, straight wire is carrying a constant current
- $d\vec{s} \times \hat{r} = (dx \sin \theta) \hat{k}$
- Integrating over all the current elements gives

$$B = -\frac{\mu_0 I}{4\pi a} \int_{\theta_1}^{\theta_2} \cos \theta \, d\theta$$
$$= \frac{\mu_0 I}{4\pi a} (\sin \theta_1 - \sin \theta_2)$$

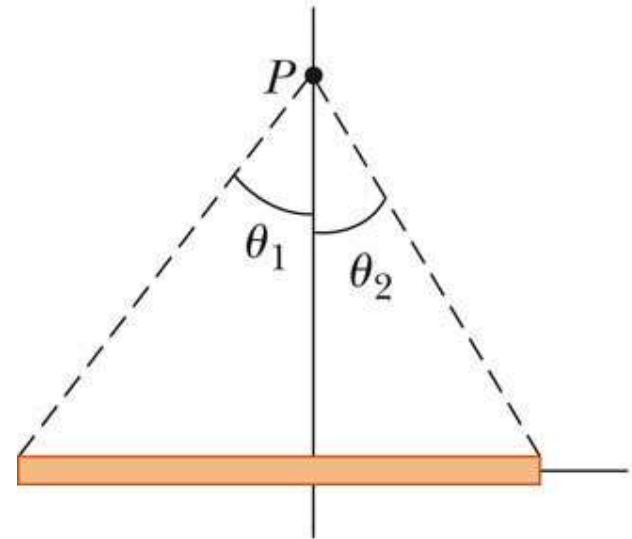


# $\vec{B}$ for a Long, Straight Conductor, Special Case



- If the conductor is an infinitely long, straight wire,  $\theta_1 = \pi/2$  and  $\theta_2 = -\pi/2$
- The field becomes

$$B = \frac{\mu_o I}{2\pi a}$$

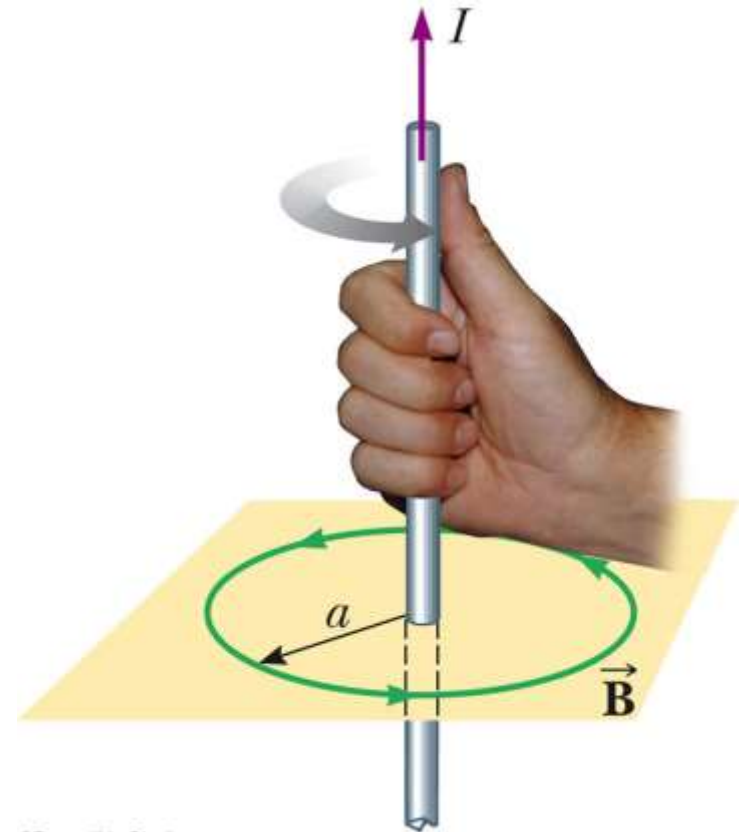


(b)

# $\vec{B}$ for a Long, Straight Conductor, Direction



- The magnetic field lines are circles concentric with the wire
- The field lines lie in planes perpendicular to the wire
- The magnitude of the field is constant on any circle of radius  $a$
- The right-hand rule for determining the direction of the field is shown



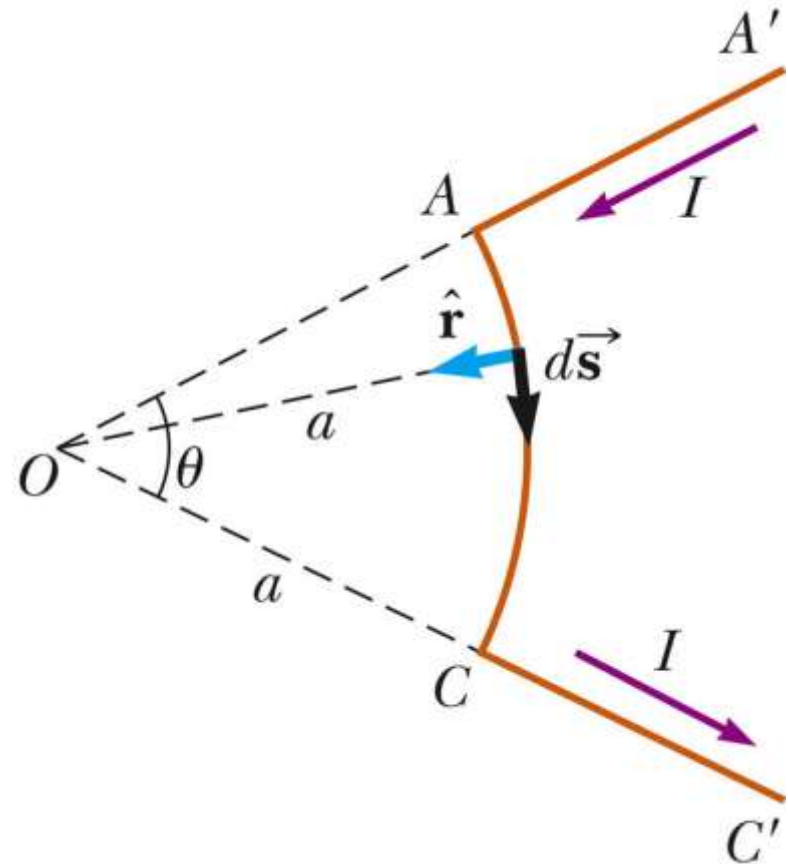
# $\vec{B}$ for a Curved Wire Segment



- Find the field at point  $O$  due to the wire segment
- $I$  and  $R$  are constants

$$B = \frac{\mu_o I}{4\pi R} \theta$$

- $\theta$  will be in radians







# $\vec{B}$ for a Circular Loop of Wire

- Consider the previous result, with a full circle

- $\theta = 2\pi$

$$B = \frac{\mu_o I}{4\pi a} \theta = \frac{\mu_o I}{4\pi a} 2\pi = \frac{\mu_o I}{2a}$$

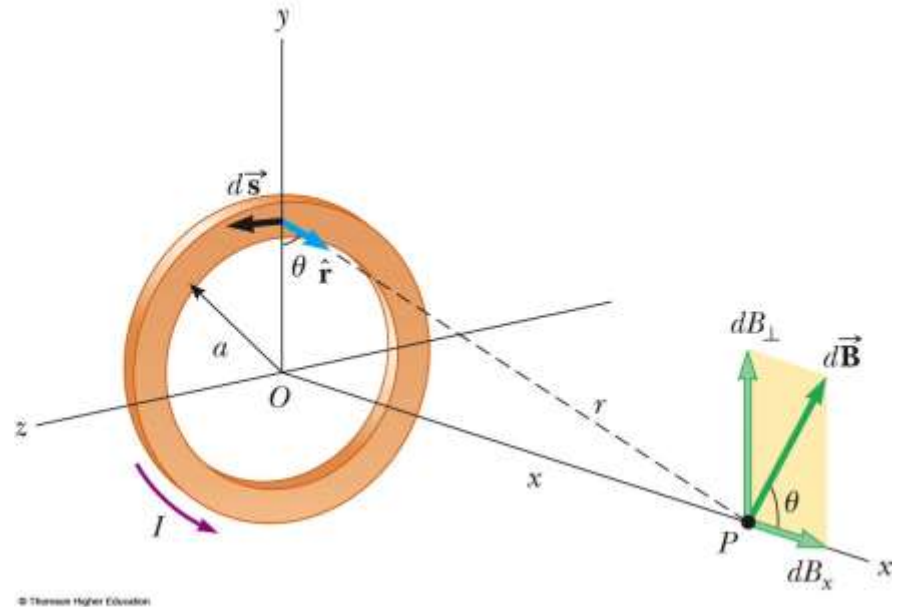
- This is the field at the *center* of the loop

# $\vec{B}$ for a Circular Current Loop



- The loop has a radius of  $R$  and carries a steady current of  $I$
- Find the field at point  $P$

$$B_x = \frac{\mu_0 I a^2}{2(a^2 + x^2)^{3/2}}$$





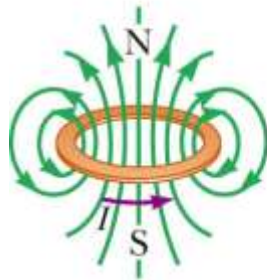
# Comparison of Loops

- Consider the field at the center of the current loop
- At this special point,  $x = 0$
- Then,

$$B_x = \frac{\mu_o I a^2}{2(a^2 + x^2)^{3/2}} = \frac{\mu_o I}{2a}$$

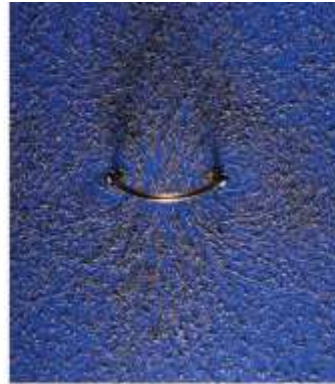
- This is exactly the same result as from the curved wire

# Magnetic Field Lines for a Loop

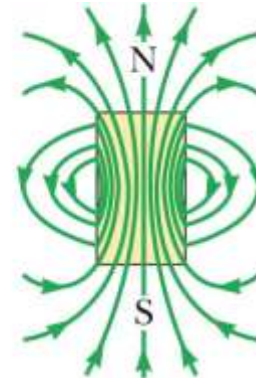


(a)

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(b)



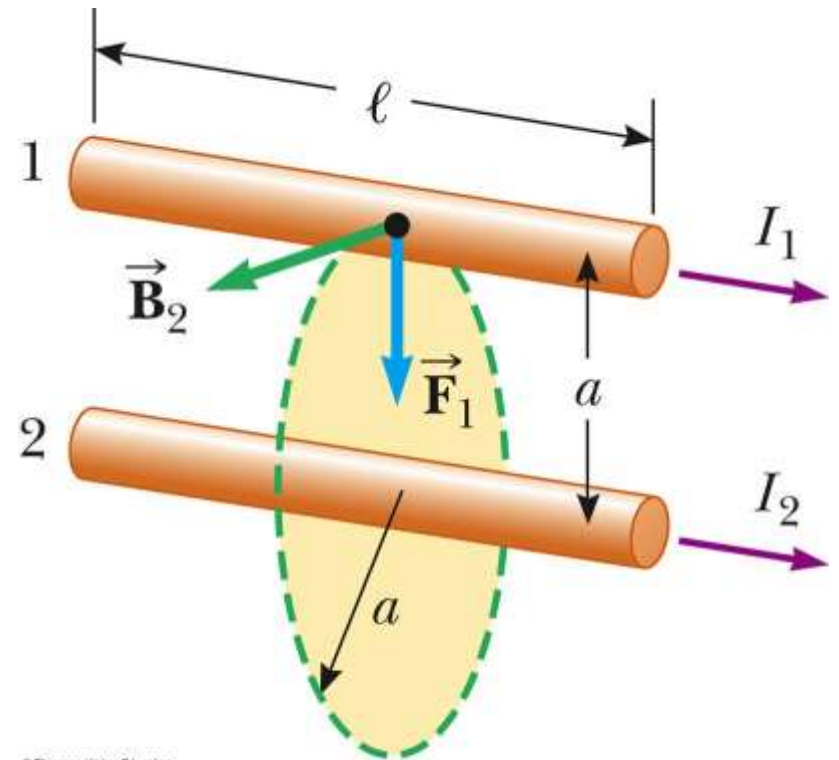
(c)

- Figure (a) shows the magnetic field lines surrounding a current loop
- Figure (b) shows the field lines in the iron filings
- Figure (c) compares the field lines to that of a bar magnet

# Magnetic Force Between Two Parallel Conductors



- Two parallel wires each carry a steady current
- The field  $\vec{B}_2$  due to the current in wire 2 exerts a force on wire 1 of  $F_1 = I_1 \ell B_2$



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ACTIVE FIGURE

# Magnetic Force Between Two Parallel Conductors, cont.



- Substituting the equation for  $\vec{\mathbf{B}}_2$  gives

$$F_1 = \frac{\mu_0 I_1 I_2 \ell}{2\pi a}$$

- Parallel conductors carrying currents in the same direction attract each other
- Parallel conductors carrying current in opposite directions repel each other

# Magnetic Force Between Two Parallel Conductors, final



- The result is often expressed as the magnetic force between the two wires,  $F_B$
- This can also be given as the force per unit length:

$$\frac{F_B}{\ell} = \frac{\mu_0 I_1 I_2}{2\pi a}$$



# Definition of the Ampere

- The force between two parallel wires can be used to define the ampere
- When the magnitude of the force per unit length between two long, parallel wires that carry identical currents and are separated by 1 m is  $2 \times 10^{-7}$  N/m, the current in each wire is defined to be 1 A





# Definition of the Coulomb

- The SI unit of charge, the coulomb, is defined in terms of the ampere
- When a conductor carries a steady current of 1 A, the quantity of charge that flows through a cross section of the conductor in 1 s is 1 C



# Andre-Marie Ampère

- 1775 – 1836
- French physicist
- Created with the discovery of electromagnetism
  - The relationship between electric current and magnetic fields
- Also worked in mathematics

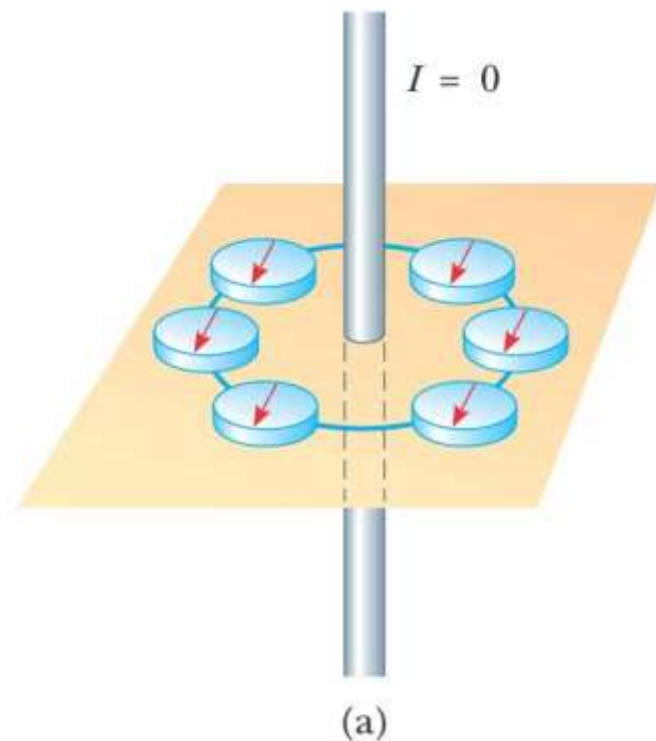


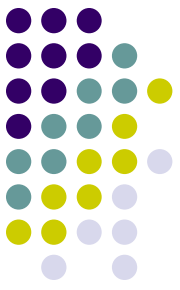
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# Magnetic Field of a Wire

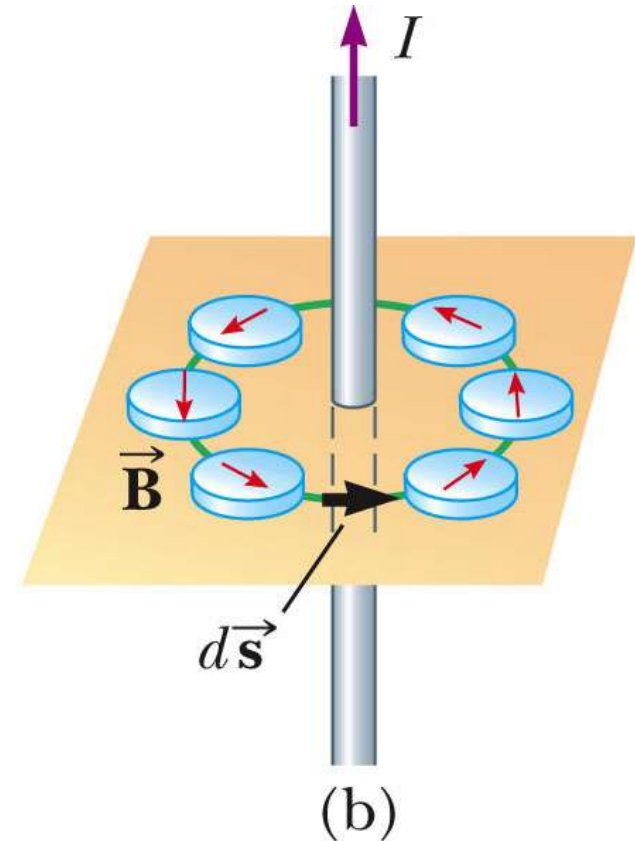
- A compass can be used to detect the magnetic field
- When there is no current in the wire, there is no field due to the current
- The compass needles all point toward the Earth's north pole
  - Due to the Earth's magnetic field





# Magnetic Field of a Wire, 2

- Here the wire carries a strong current
- The compass needles deflect in a direction tangent to the circle
- This shows the direction of the magnetic field produced by the wire
- Use the active figure to vary the current



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ACTIVE FIGURE

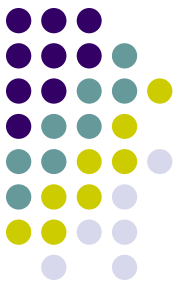
# Magnetic Field of a Wire, 3



- The circular magnetic field around the wire is shown by the iron filings



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# Ampere's Law

- The product of  $\vec{\mathbf{B}} \cdot d\vec{\mathbf{s}}$  can be evaluated for small length elements  $d\vec{\mathbf{s}}$  on the circular path defined by the compass needles for the long straight wire
- Ampere's law states that the line integral of  $\vec{\mathbf{B}} \cdot d\vec{\mathbf{s}}$  around any closed path equals  $\mu_0 I$  where  $I$  is the total steady current passing through any surface bounded by the closed path: 
$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = \mu_0 I$$



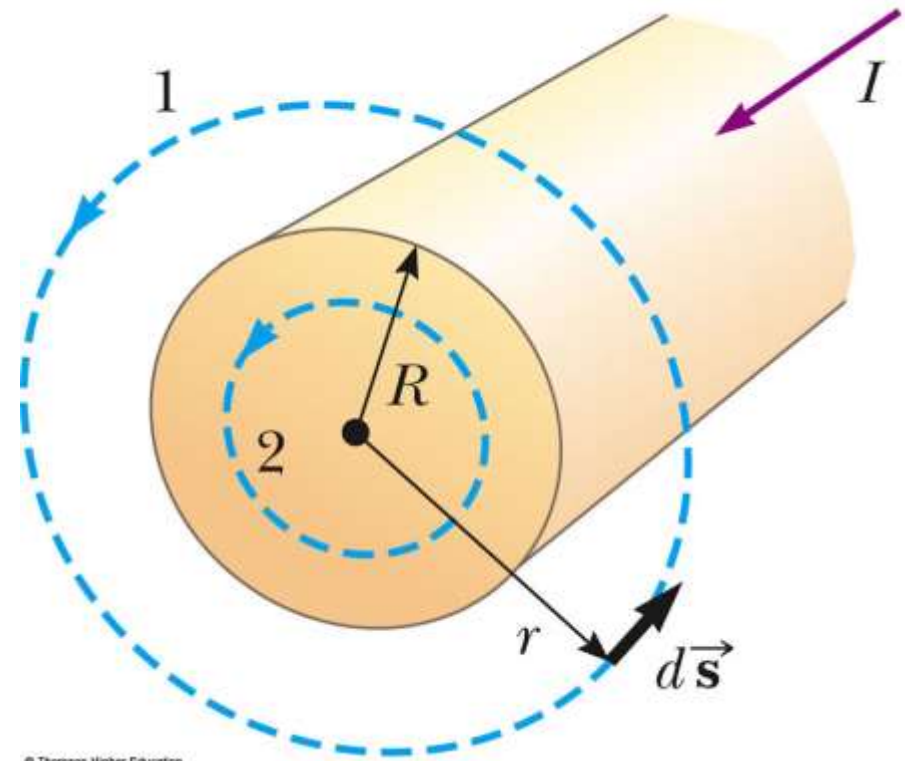
# Ampere's Law, cont.

- Ampere's law describes the creation of magnetic fields by all continuous current configurations
  - Most useful for this course if the current configuration has a high degree of symmetry
- Put the thumb of your right hand in the direction of the current through the amperian loop and your fingers curl in the direction you should integrate around the loop

# Field Due to a Long Straight Wire – From Ampere's Law

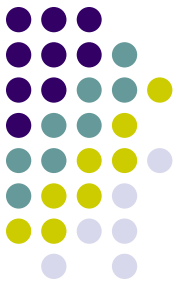


- Want to calculate the magnetic field at a distance  $r$  from the center of a wire carrying a steady current  $I$
- The current is uniformly distributed through the cross section of the wire





# Field Due to a Long Straight Wire – Results From Ampere's Law



- Outside of the wire,  $r > R$

$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B(2\pi r) = \mu_0 I \quad \rightarrow \quad B = \frac{\mu_0 I}{2\pi r}$$

- Inside the wire, we need  $I'$ , the current inside the amperian circle

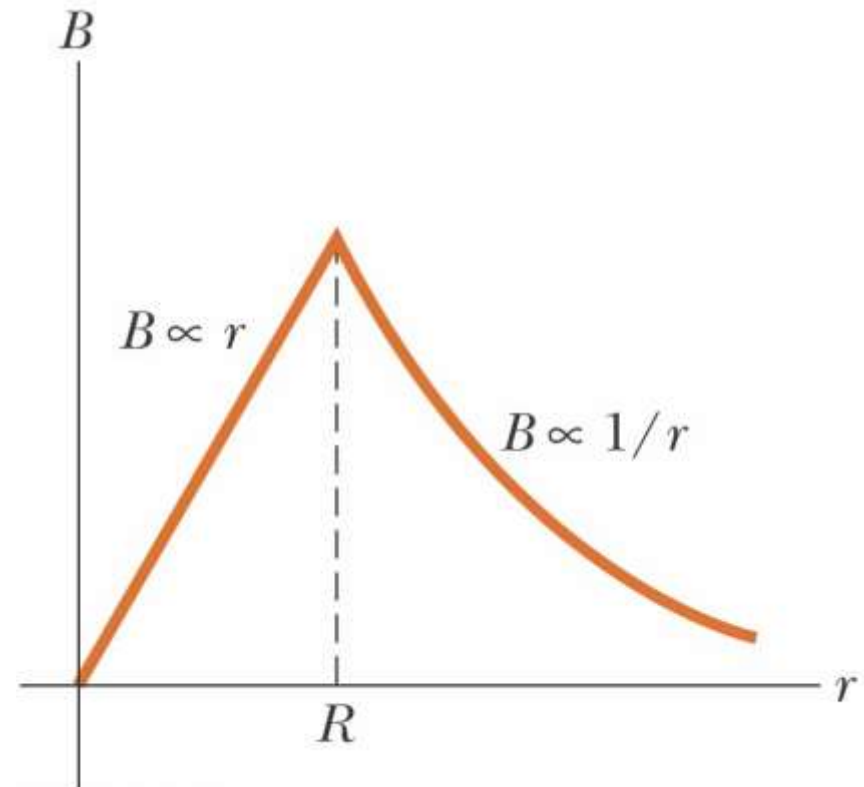
$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B(2\pi r) = \mu_0 I' \quad \rightarrow \quad I' = \frac{r^2}{R^2} I$$

$$B = \left( \frac{\mu_0 I}{2\pi R^2} \right) r$$

# Field Due to a Long Straight Wire – Results Summary



- The field is proportional to  $r$  inside the wire
- The field varies as  $1/r$  outside the wire
- Both equations are equal at  $r = R$



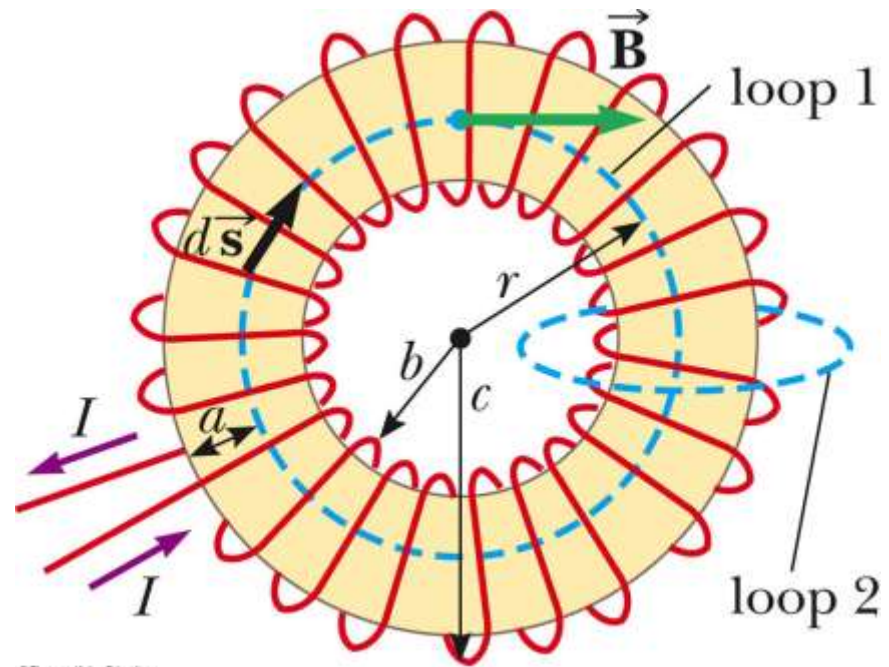


# Magnetic Field of a Toroid

- Find the field at a point at distance  $r$  from the center of the toroid
- The toroid has  $N$  turns of wire

$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B(2\pi r) = \mu_0 N I$$

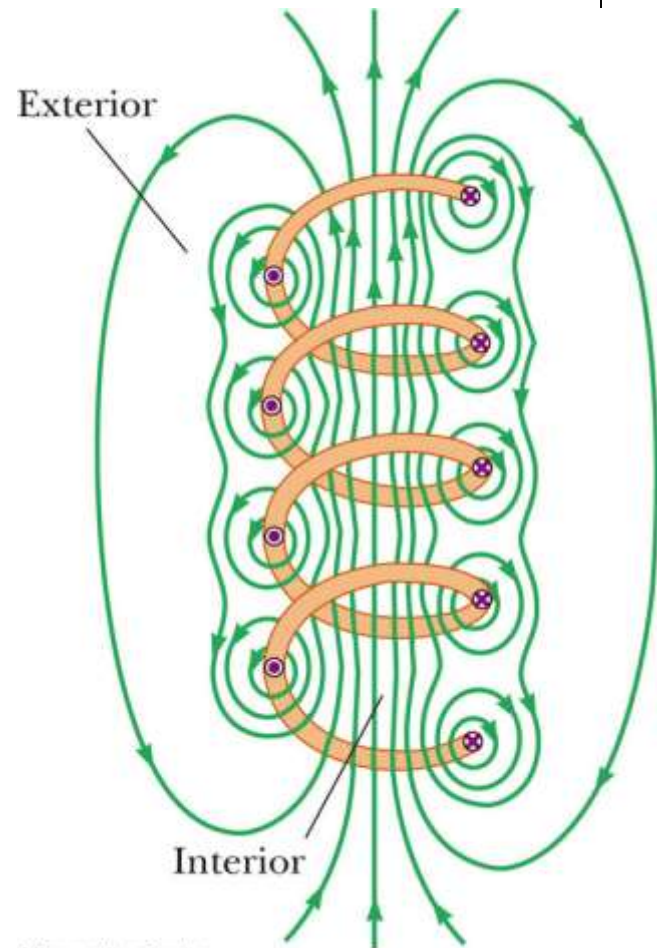
$$B = \frac{\mu_0 N I}{2\pi r}$$





# Magnetic Field of a Solenoid

- A **solenoid** is a long wire wound in the form of a helix
- A reasonably uniform magnetic field can be produced in the space surrounded by the turns of the wire
  - The *interior* of the solenoid



# Magnetic Field of a Solenoid, Description

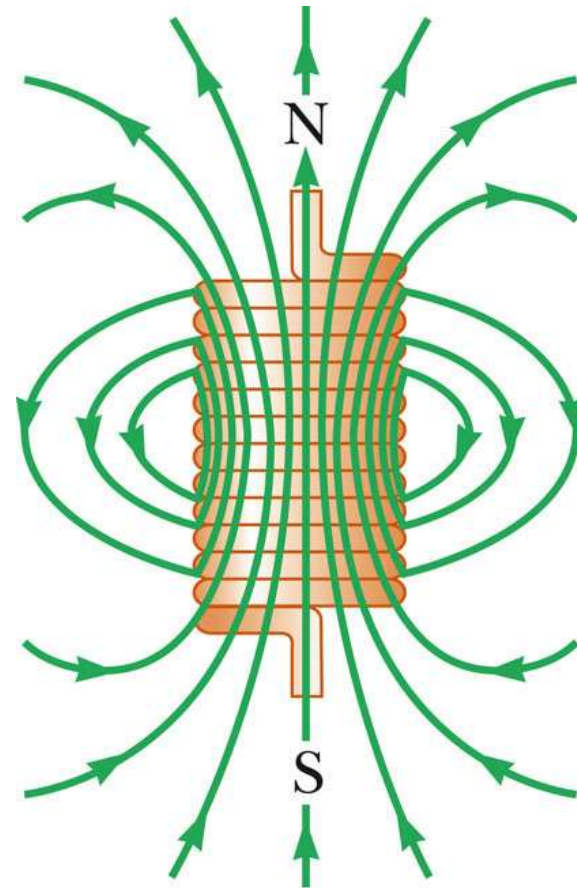


- The field lines in the interior are
  - nearly parallel to each other
  - uniformly distributed
  - close together
- This indicates the field is strong and almost uniform

# Magnetic Field of a Tightly Wound Solenoid



- The field distribution is similar to that of a bar magnet
- As the length of the solenoid increases
  - the interior field becomes more uniform
  - the exterior field becomes weaker

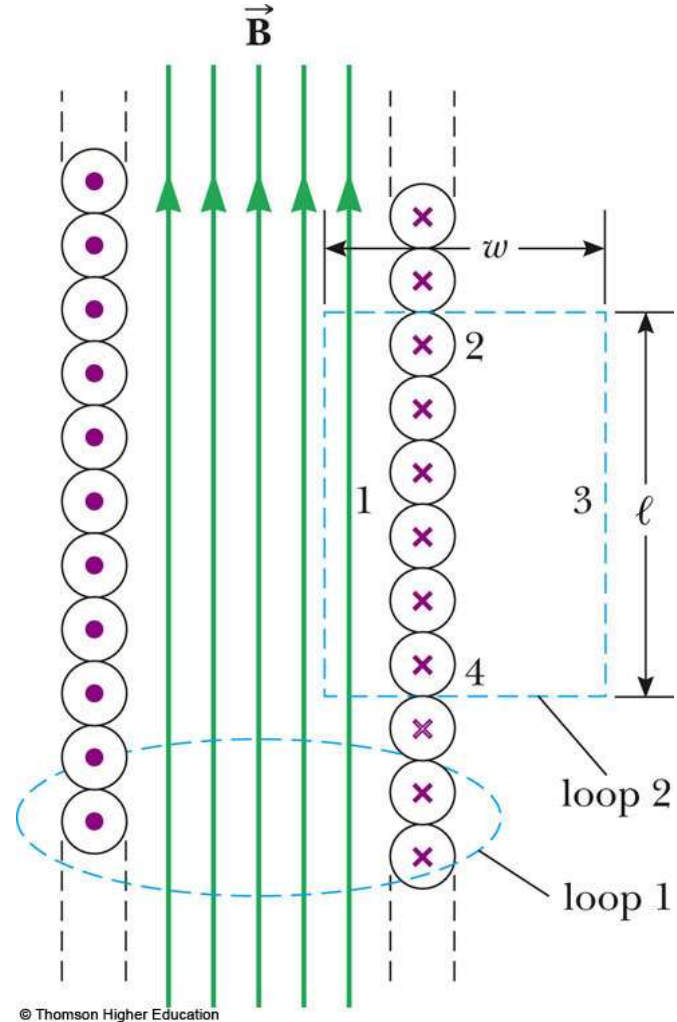


(a)

# Ideal Solenoid – Characteristics



- An *ideal solenoid* is approached when:
  - the turns are closely spaced
  - the length is much greater than the radius of the turns



# Ampere's Law Applied to a Solenoid



- Ampere's law can be used to find the interior magnetic field of the solenoid
- Consider a rectangle with side  $\ell$  parallel to the interior field and side  $w$  perpendicular to the field
  - This is loop 2 in the diagram
- The side of length  $\ell$  inside the solenoid contributes to the field
  - This is side 1 in the diagram



# Ampere's Law Applied to a Solenoid, cont.



- Applying Ampere's Law gives

$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = \int_{path1} \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B \int_{path1} ds = B\ell$$

- The total current through the rectangular path equals the current through each turn multiplied by the number of turns

$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B\ell = \mu_0 NI$$

# Magnetic Field of a Solenoid, final



- Solving Ampere's law for the magnetic field is

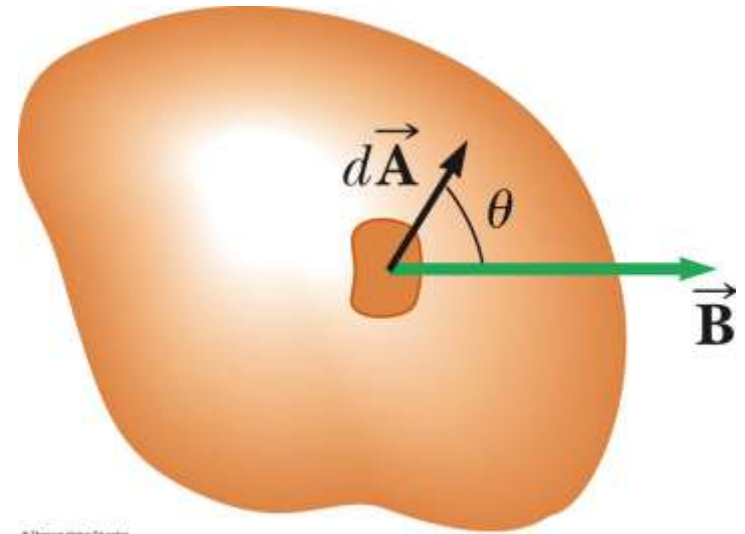
$$B = \mu_0 \frac{N}{\ell} I = \mu_0 n I$$

- $n = N / \ell$  is the number of turns per unit length
- This is valid only at points near the center of a very long solenoid



# Magnetic Flux

- The magnetic flux associated with a magnetic field is defined in a way similar to electric flux
- Consider an area element  $dA$  on an arbitrarily shaped surface





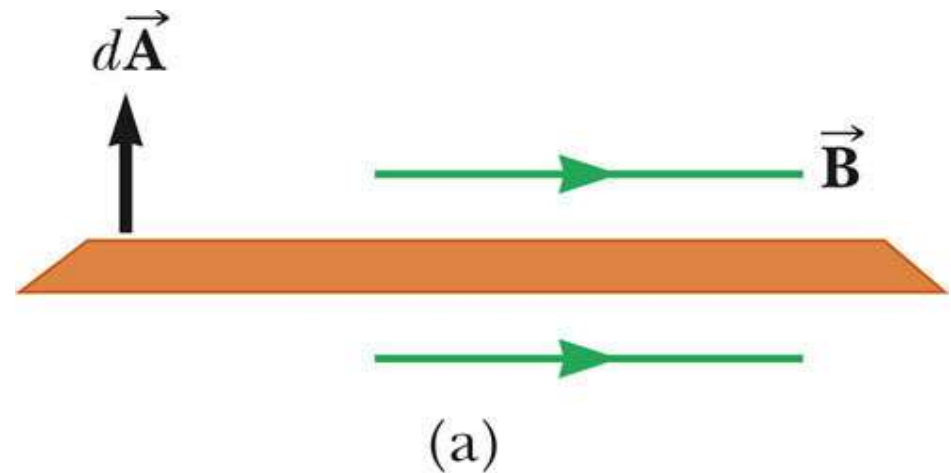
# Magnetic Flux, cont.

- The magnetic field in this element is  $\vec{\mathbf{B}}$
- $d\vec{\mathbf{A}}$  is a vector that is perpendicular to the surface
- $d\vec{\mathbf{A}}$  has a magnitude equal to the area  $dA$
- The magnetic flux  $\Phi_B$  is
$$\Phi_B = \int \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}}$$
- The unit of magnetic flux is  $\text{T}\cdot\text{m}^2 = \text{Wb}$ 
  - Wb is a *weber*

# Magnetic Flux Through a Plane, 1



- A special case is when a plane of area  $A$  makes an angle  $\theta$  with  $d\vec{A}$
- The magnetic flux is  $\Phi_B = BA \cos \theta$
- In this case, the field is parallel to the plane and  $\Phi = 0$

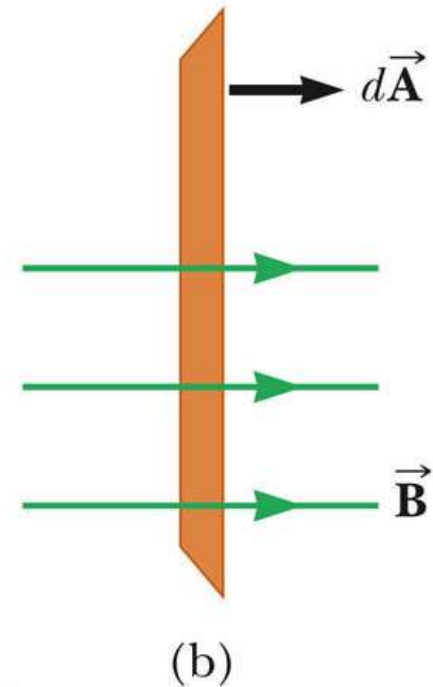


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ACTIVE FIGURE

# Magnetic Flux Through A Plane, 2



- The magnetic flux is  $\Phi_B = BA \cos \theta$
- In this case, the field is perpendicular to the plane and  
 $\Phi = BA$
- This will be the maximum value of the flux
- Use the active figure to investigate different angles



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ACTIVE FIGURE



# Gauss' Law in Magnetism

- Magnetic fields do not begin or end at any point
  - The number of lines entering a surface equals the number of lines leaving the surface
- **Gauss' law in magnetism** says the magnetic flux through any closed surface is always zero:

$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}} = 0$$

# Magnetic Moments



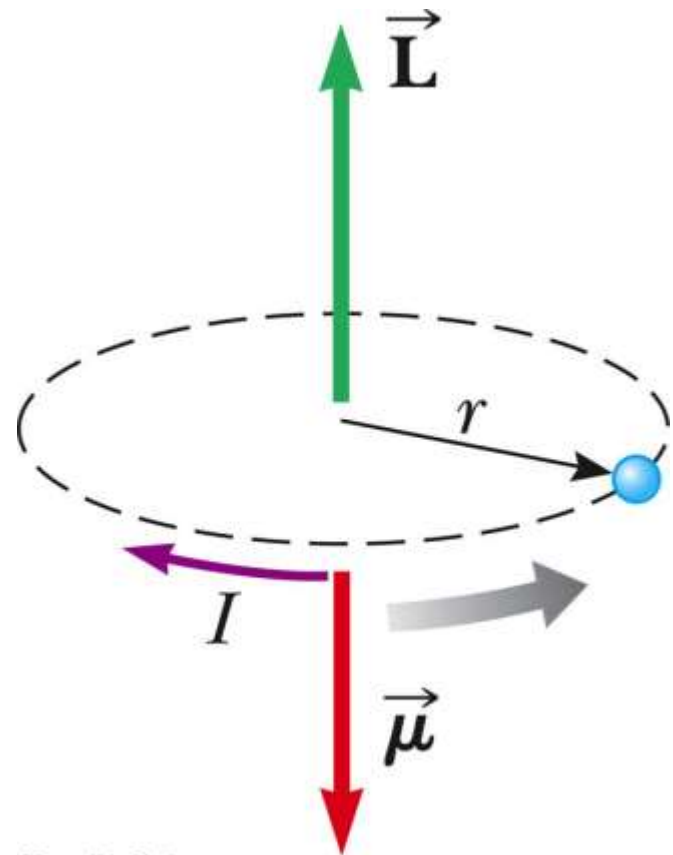
- In general, any current loop has a magnetic field and thus has a magnetic dipole moment
- This includes atomic-level current loops described in some models of the atom
- This will help explain why some materials exhibit strong magnetic properties



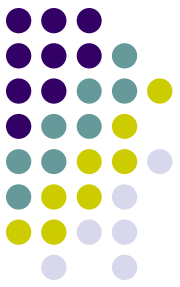
# Magnetic Moments – Classical Atom



- The electrons move in circular orbits
- The orbiting electron constitutes a tiny current loop
- The magnetic moment of the electron is associated with this orbital motion
- $\vec{L}$  is the angular momentum
- $\vec{\mu}$  is magnetic moment



# Magnetic Moments – Classical Atom, 2



- This model assumes the electron moves
  - with constant speed  $v$
  - in a circular orbit of radius  $r$
  - travels a distance  $2\pi r$  in a time interval  $T$
- The current associated with this orbiting electron is

$$I = \frac{e}{T} = \frac{ev}{2\pi r}$$

# Magnetic Moments – Classical Atom, 3



- The magnetic moment is  $\mu = I A = \frac{1}{2} e v r$
- The magnetic moment can also be expressed in terms of the angular momentum

$$\mu = \left( \frac{e}{2m_e} \right) L$$

# Magnetic Moments – Classical Atom, final



- The magnetic moment of the electron is proportional to its orbital angular momentum
  - The vectors  $\vec{L}$  and  $\vec{\mu}$  point in *opposite* directions
  - Because the electron is negatively charged
- Quantum physics indicates that angular momentum is quantized

# Magnetic Moments of Multiple Electrons

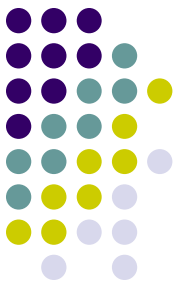


- In most substances, the magnetic moment of one electron is canceled by that of another electron orbiting in the same direction
- The net result is that the magnetic effect produced by the orbital motion of the electrons is either zero or very small

# Electron Spin



- Electrons (and other particles) have an intrinsic property called **spin** that also contributes to their magnetic moment
  - The electron is not physically spinning
  - It has an intrinsic angular momentum as if it were spinning
  - Spin angular momentum is actually a relativistic effect

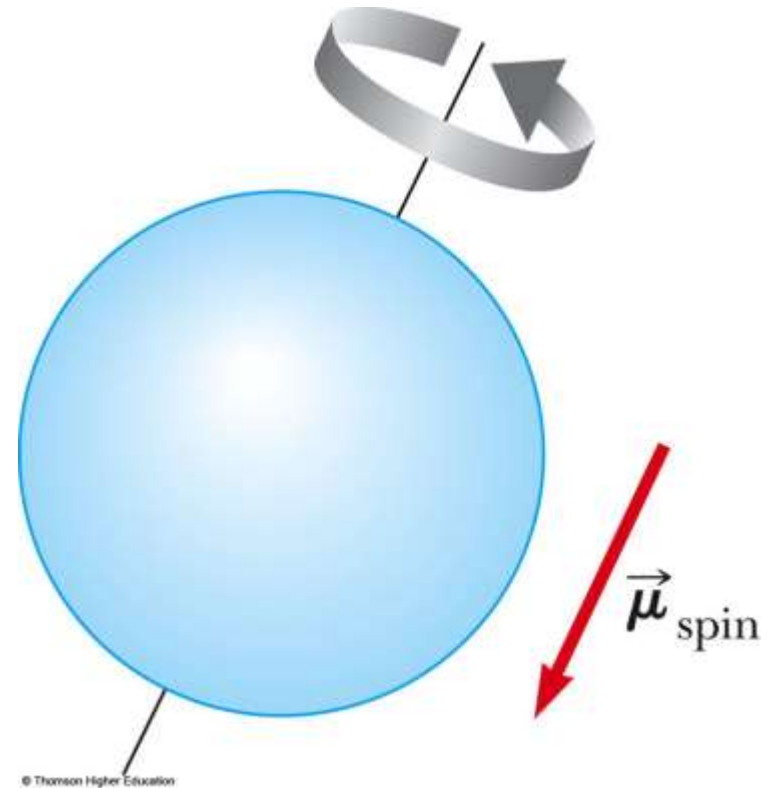


# Electron Spin, cont.

- The classical model of electron spin is the electron spinning on its axis
- The magnitude of the spin angular momentum is

$$S = \frac{\sqrt{3}}{2} \hbar$$

- $\hbar$  is Planck's constant



# Electron Spin and Magnetic Moment



- The magnetic moment characteristically associated with the spin of an electron has the value

$$\mu_{\text{spin}} = \frac{e\hbar}{2m_e}$$

- This combination of constants is called the **Bohr magneton**  $\mu_B = 9.27 \times 10^{-24} \text{ J/T}$



# Electron Magnetic Moment, final



- The total magnetic moment of an atom is the vector sum of the orbital and spin magnetic moments
- Some examples are given in the table at right
- The magnetic moment of a proton or neutron is much smaller than that of an electron and can usually be neglected

**TABLE 30.1**

**Magnetic Moments of Some Atoms and Ions**

Atom or Ion	Magnetic Moment ( $10^{-24}$ J/T)
H	9.27
He	0
Ne	0
Ce <sup>3+</sup>	19.8
Yb <sup>3+</sup>	37.1



# Ferromagnetism

- Some substances exhibit strong magnetic effects called ferromagnetism
- Some examples of ferromagnetic materials are:
  - iron
  - cobalt
  - nickel
  - gadolinium
  - dysprosium
- They contain permanent atomic magnetic moments that tend to align parallel to each other even in a weak external magnetic field



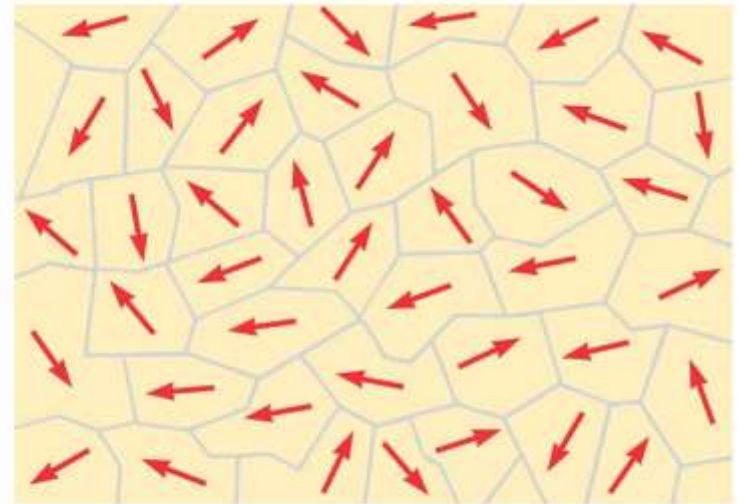
# Domains

- All ferromagnetic materials are made up of microscopic regions called **domains**
  - The domain is an area within which all magnetic moments are aligned
- The boundaries between various domains having different orientations are called **domain walls**

# Domains, Unmagnetized Material



- The magnetic moments in the domains are randomly aligned
- The net magnetic moment is zero

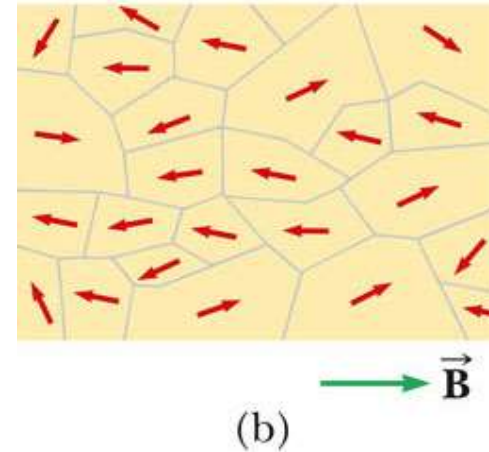


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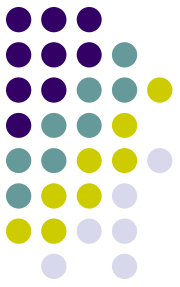
# Domains, External Field Applied



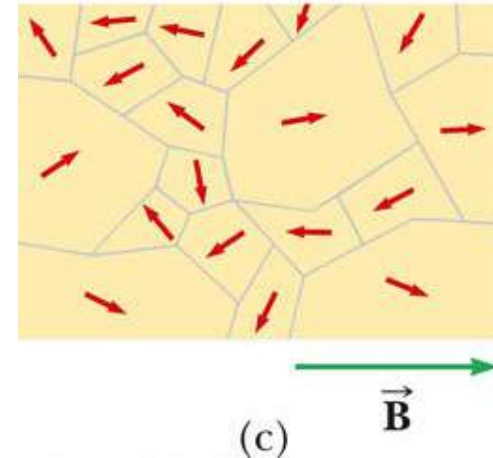
- A sample is placed in an external magnetic field
- The size of the domains with magnetic moments aligned with the field grows
- The sample is magnetized

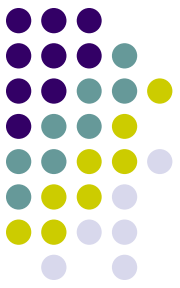


# Domains, External Field Applied, cont.



- The material is placed in a stronger field
- The domains not aligned with the field become very small
- When the external field is removed, the material may retain a net magnetization in the direction of the original field





# Curie Temperature

- The **Curie temperature** is the critical temperature above which a ferromagnetic material loses its residual magnetism
  - The material will become paramagnetic
- Above the Curie temperature, the thermal agitation is great enough to cause a random orientation of the moments

# Table of Some Curie Temperatures



**TABLE 30.2**

## Curie Temperatures for Several Ferromagnetic Substances

Substance	$T_{\text{Curie}}$ (K)
Iron	1 043
Cobalt	1 394
Nickel	631
Gadolinium	317
$\text{Fe}_2\text{O}_3$	893



# Paramagnetism



- Paramagnetic substances have small but positive magnetism
- It results from the presence of atoms that have permanent magnetic moments
  - These moments interact weakly with each other
- When placed in an external magnetic field, its atomic moments tend to line up with the field
  - The alignment process competes with thermal motion which randomizes the moment orientations

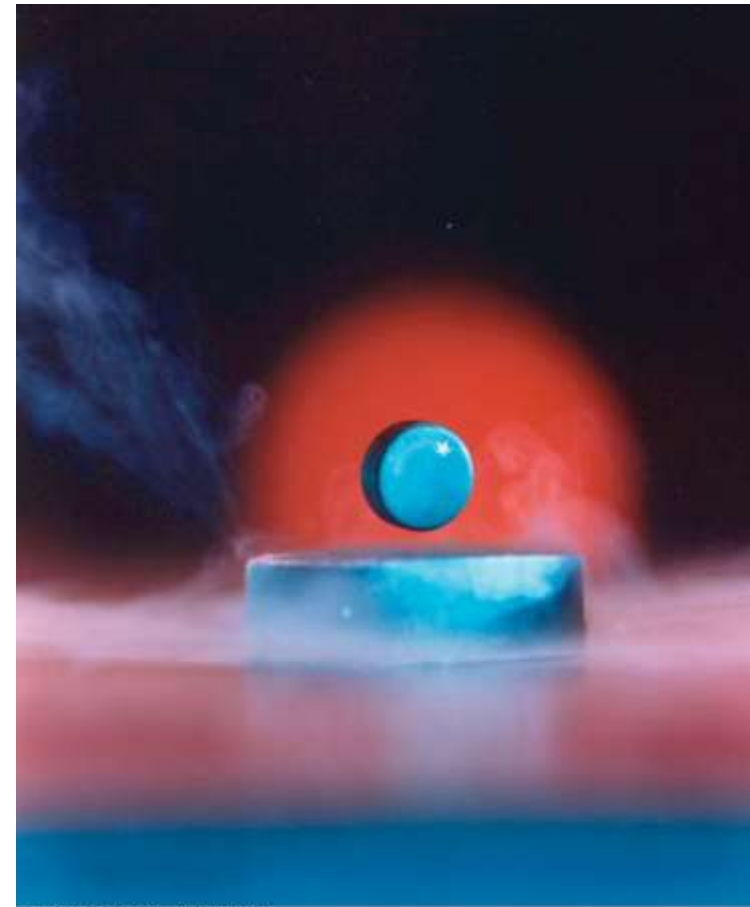


# Diamagnetism

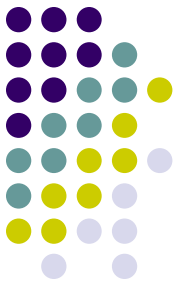
- When an external magnetic field is applied to a diamagnetic substance, a weak magnetic moment is induced in the direction opposite the applied field
- Diamagnetic substances are weakly repelled by a magnet
  - Weak, so only present when ferromagnetism or paramagnetism do not exist

# Meissner Effect

- Certain types of superconductors also exhibit perfect diamagnetism in the superconducting state
  - This is called the **Meissner effect**
- If a permanent magnet is brought near a superconductor, the two objects repel each other



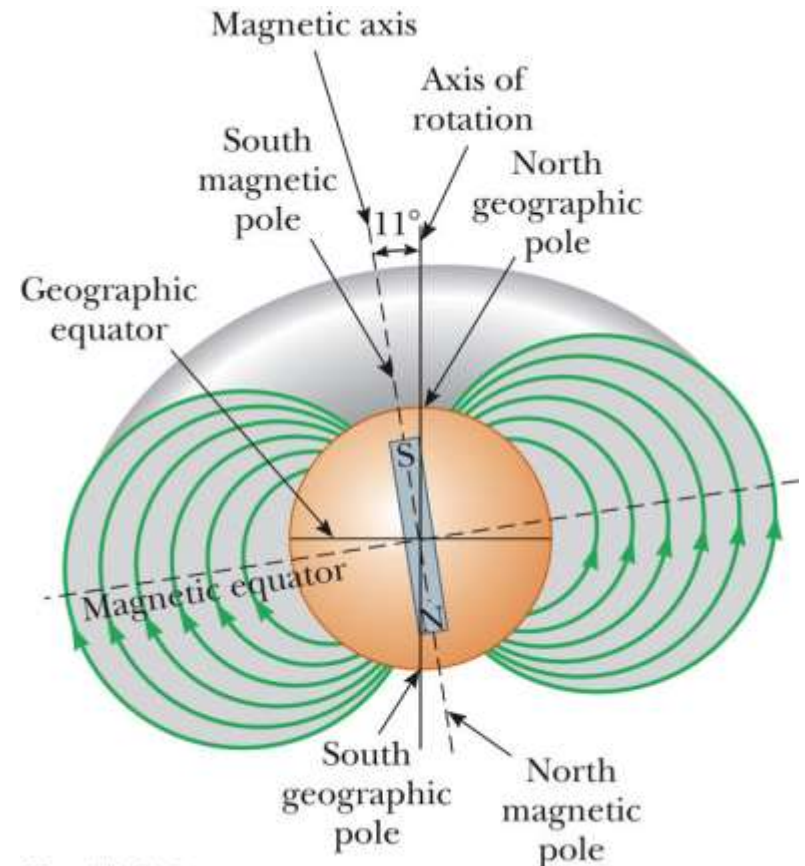
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# Earth's Magnetic Field

- The Earth's magnetic field resembles that achieved by burying a huge bar magnet deep in the Earth's interior
- The Earth's south magnetic pole is located near the north geographic pole
- The Earth's north magnetic pole is located near the south geographic pole



# Vertical Movement of a Compass



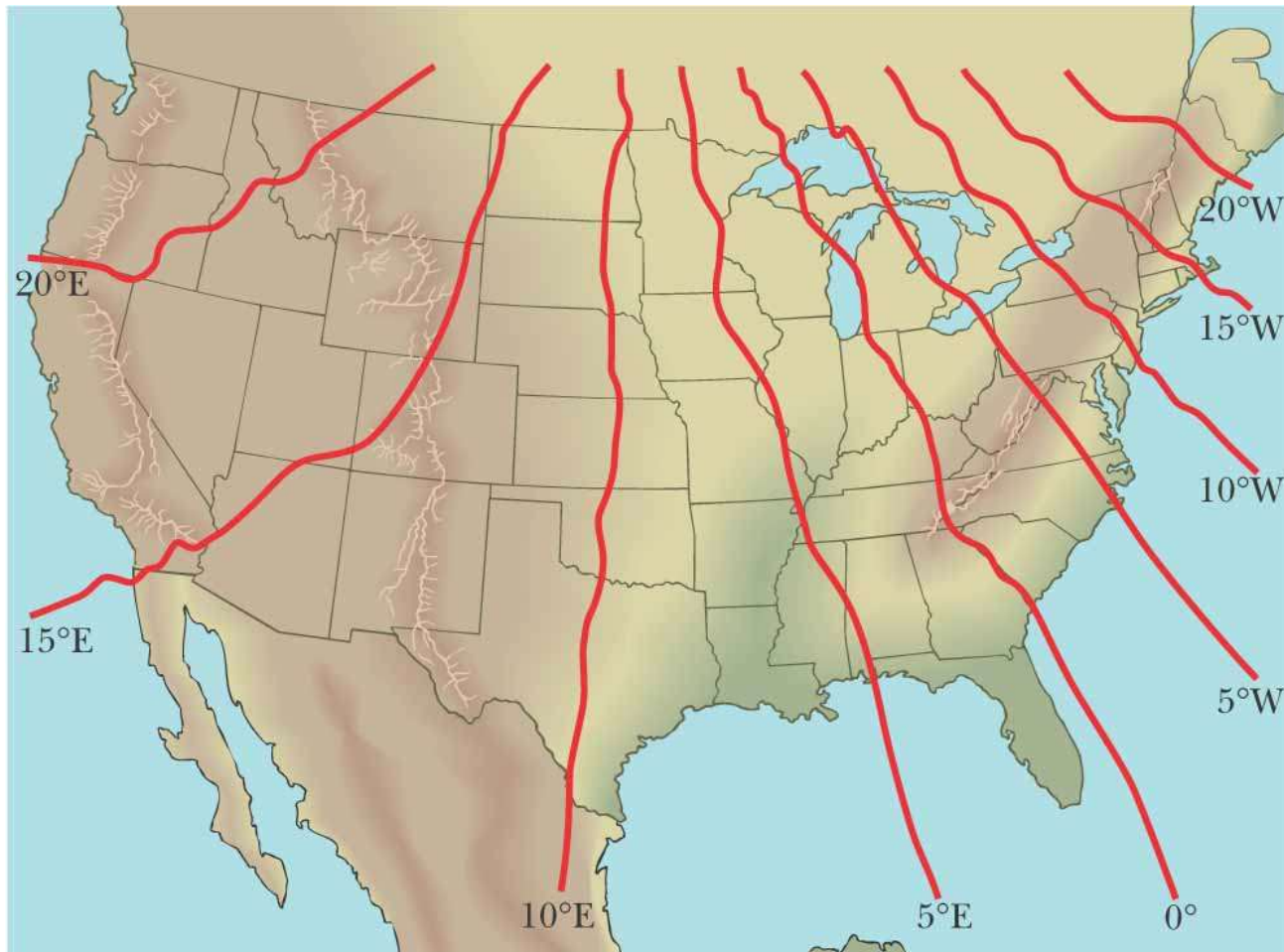
- If a compass is free to rotate vertically as well as horizontally, it points to the Earth's surface
- The farther north the device is moved, the farther from horizontal the compass needle would be
  - The compass needle would be horizontal at the equator
  - The compass needle would point straight down at the magnetic pole

# More About the Earth's Magnetic Poles



- The compass needle with point straight downward found at a point just north of Hudson Bay in Canada
  - This is considered to be the location of the south magnetic pole
  - The exact location varies slowly with time
- The magnetic and geographic poles are not in the same exact location
  - The difference between true north, at the geographic north pole, and magnetic north is called the magnetic declination
    - The amount of declination varies by location on the Earth's surface

# Earth's Magnetic Declination



# Source of the Earth's Magnetic Field



- There cannot be large masses of permanently magnetized materials since the high temperatures of the core prevent materials from retaining permanent magnetization
- The most likely source of the Earth's magnetic field is believed to be convection currents in the liquid part of the core
- There is also evidence that the planet's magnetic field is related to its rate of rotation



# Reversals of the Earth's Magnetic Field



- The direction of the Earth's magnetic field reverses every few million years
  - Evidence of these reversals are found in basalts resulting from volcanic activity
  - The rocks provide a timeline for the periodic reversals of the field
    - The rocks are dated by other means to determine the timeline